

# Automatic Design of ORC Turbine Profiles Using Evolutionary Algorithms

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# Design of ORC turbines

Turbomachinery design demands systematic procedures

ORCs push towards non-conventional turbomachinery (load, efficiency, compactness)

Semi-empirical criteria lack of reliability in non-conventional contexts

High-fidelity CFD crucial in non-conventional turbomachinery R&D

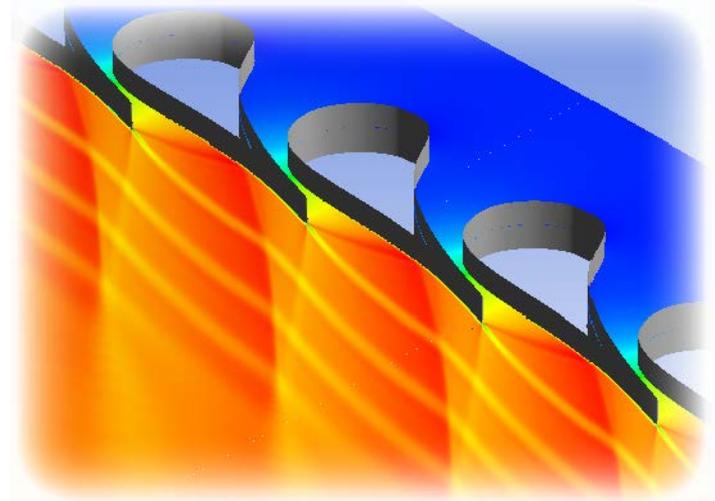
Automatic CFD-based design package required

**Evolutionary design strategy** coupled with:

geometric **parametrization** methods

experimentally validated **CFD model**

**surrogate** models

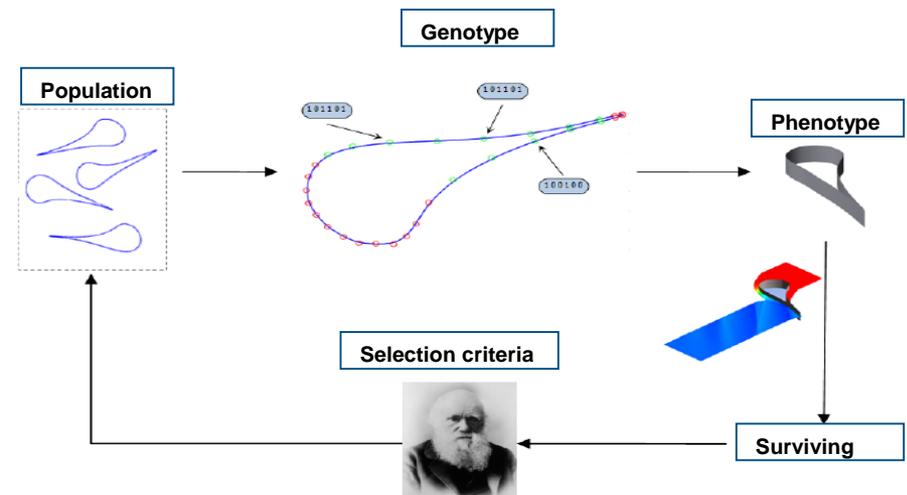


# Outline

- Evolutionary Shape Optimization
- Bricks
  - ✓ Parametrization model
  - ✓ CFD model
  - ✓ Surrogate model
- Optimization Strategy Layouts
- Exercise of Design
- Robust Design
- Conclusions

# Evolutionary Shape Optimization

- **Shape Optimization**: to minimize an OF using geometry as design parameters
- Stochastic **Evolutionary** Optimization (inspired by Evolution Theory):
  - ✓ Direct: no need of problem inversion, only need direct CFD tools
  - ✓ Heuristic: requires statistical relevance (→ high cost)
- Combined with **surrogate models** to tackle computational cost
- Non-dominated Sorting **Genetic Algorithm**: **GA SCHEMATIC**
  - ✓ 200 generation
  - ✓ 70% of crossover
  - ✓ 2% of mutation
  - ✓ elitism



# Briks

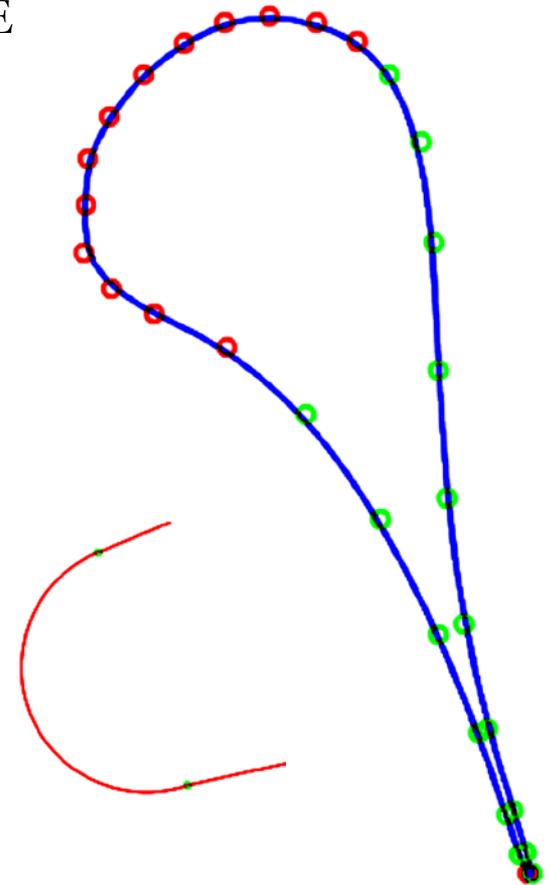
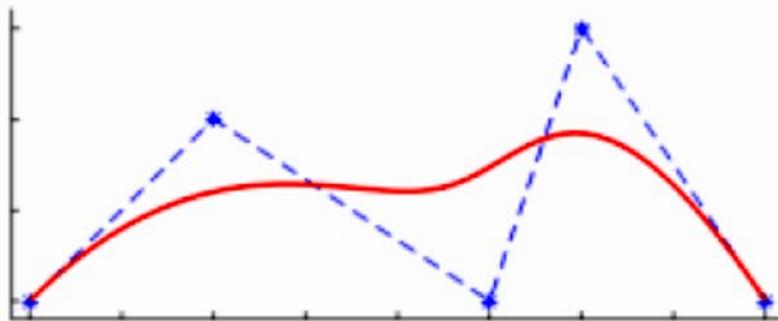
## Blade geometry parametrization

- Concept: blade geometry as succession of regular lines identified by **Control Points**
- **B-Spline** cubic lines:  $C^2$  smoothness, identified by 4 CPs, computed recursively
- Degrees of **freedom**: impose passing by CPs, circular TE

$$x(u) = \sum_{j=0}^L d_j N_j^n(u)$$

$$N_j^k(u) = \frac{u - u_{j-1}}{u_{j+k-1} - u_{j-1}} N_j^{k-1}(u) + \frac{u_{j+k} - u}{u_{j+k} - u_j} N_{j+1}^{k-1}(u)$$

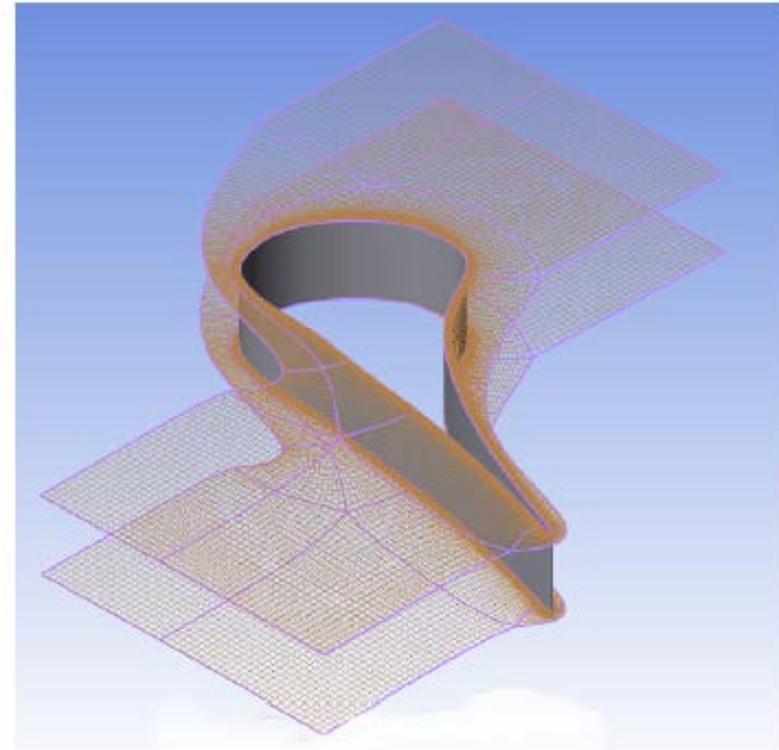
$$N_j^0(u) = \begin{cases} 0 & \text{if } u_{j-1} \leq u < u_j \\ 1 & \text{if otherwise} \end{cases}$$



# Briks

## CFD model

- High-fidelity blade-to-blade flow model
- Quasi-3D steady flow model
- Hexahedral grids with  $50 \div 400$  kcells
- Solver: Finite Volume ANSYS-CFX, with:
  - **HR methods** for inviscid fluxes
  - centred scheme for diffusive terms
- Turbulence model: **k- $\omega$  SST** with near-wall boundary layer solution (wall  $y^+ \sim 0.1$ )
- **Real gas model** implemented via **Look-Up-Table** approach; LuT constructed using a generalized thermodynamic library
- Flow model **validated** against experiments (Persico et al., 2012, ASME J. Turbomach.)



## Surrogate model

- $10^4$  OF evaluations required by GA, CFD runs are expensive  
→ **surrogate models** to speed-up convergence
- Surrogate: analytical function that mimics the ‘response surface’, being:
  - ✓ highly **flexible**
  - ✓ initially **tunable**
  - ✓ **adjustable** via a learning process
- **Re-tuning** of the surrogate model
  - ✓ Initial interpolation on a data-base (DOE)
  - ✓ GA only applied to the interpolated surrogate model
  - ✓ Improvement of data-base and re-interpolation close to the optimum
- **Kriging** surrogate model used (suitable for highly irregular data distributions):

# Optimization Strategy: Local vs Global

- ✓ Initial CFD-based DOE for response sampling
- ✓ Surrogate function interpolated and minimized

## Local 'trust region' method

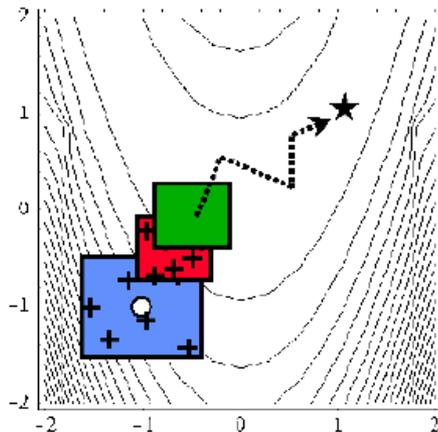
- ✓ Trust region reliability checked by trust ratio

$$\rho^k = \frac{f(x_c^k) - f(x_{opt}^k)}{\tilde{f}(x_c^k) - \tilde{f}(x_{opt}^k)}$$

- ✓ If reliable ( $\rho^k > 0.5$ ), trust region shrink
- ✓ CFD-based DOE in new trust region

...

→ Trust region collapses on optimum

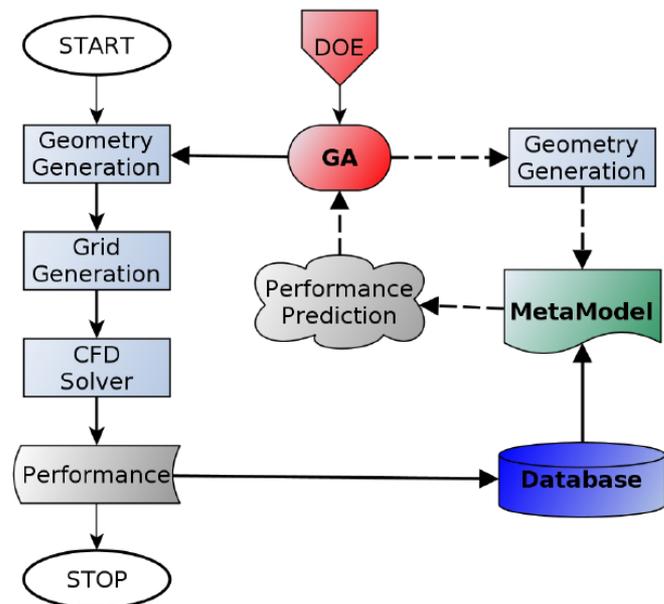


## Global 'training' method

- ✓ Optimum checked by CFD
- ✓ New CFD value added to data-base
- ✓ Surrogate re-interpolated

...

→ Surrogate minimum approaches optimum



# Exercise of Design

## Test case

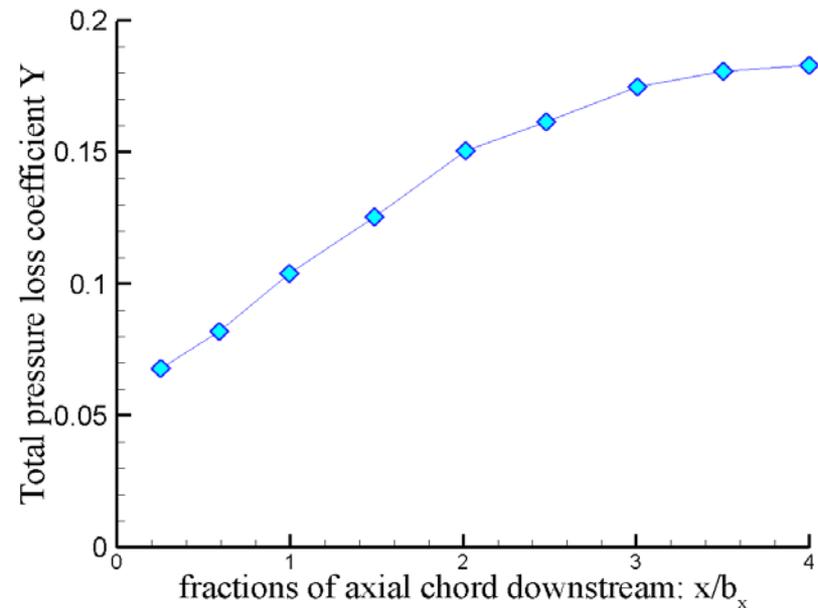
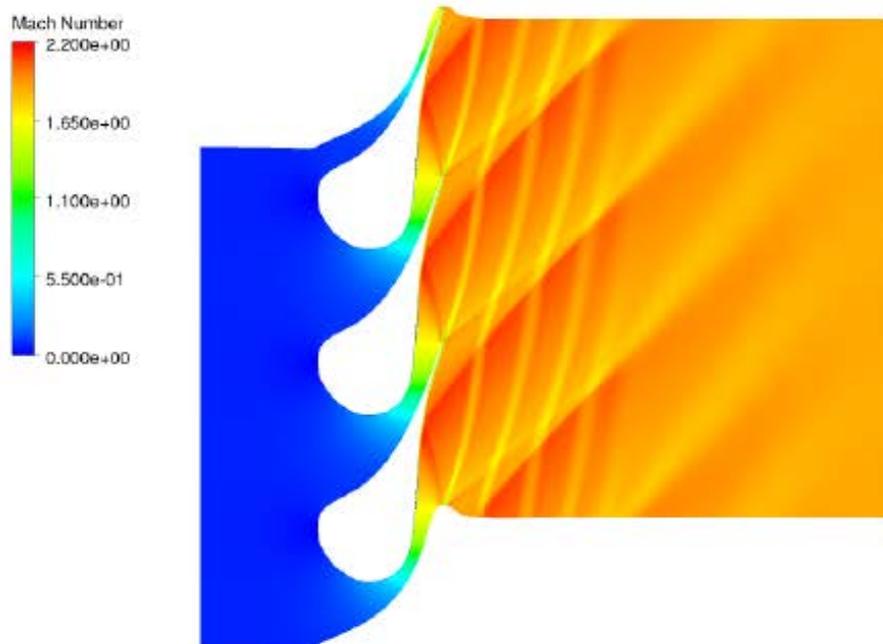
Supersonic converging-diverging cascade ( $M = 2.1$ ) for axial ORC turbine (MDM)

Baseline configuration:

Strong shocks generated on Suction Side and on TE (fishtail)

Weaving wake trace due to huge circumferential pressure gradients

→ dramatic raise of loss due to shock mixing downstream (and impact on rotor?)



# Exercise of Design

## Procedure

### Objective Function

Standard deviation of static pressure half a chord downstream of the TE

→ Minimize shock, shock mixing loss, flow disuniformity in stator-rotor gap

### Design Space

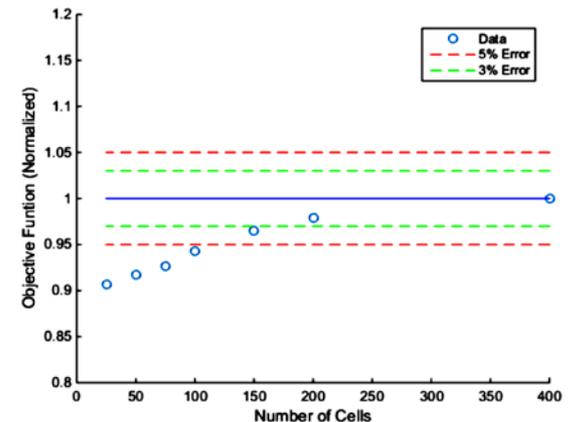
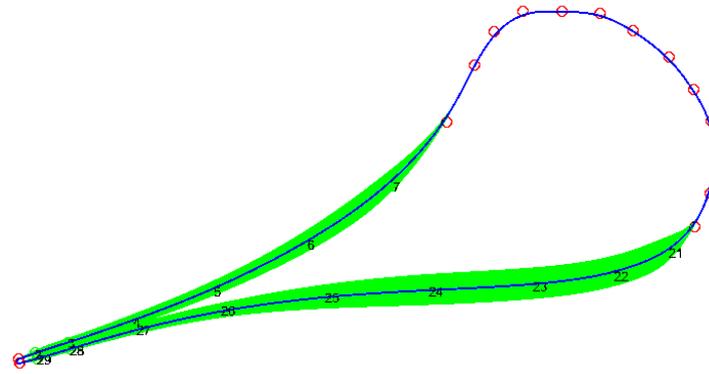
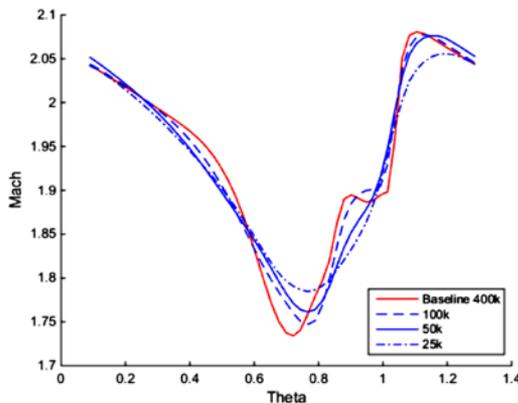
Parametric study on CP number and design space initially performed

15 movable CPs in the rear blade section both on PS and SS

### Computational Cost

grid dependence analysis to reduce the cost of CFD run

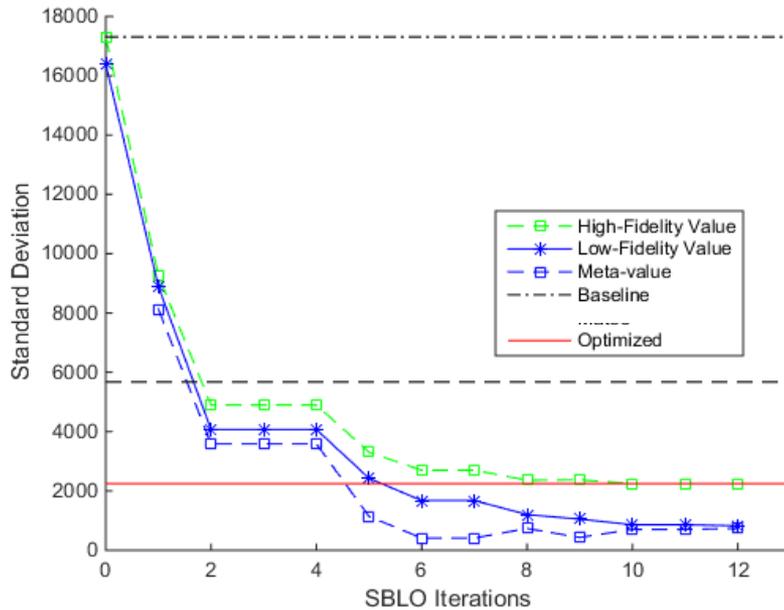
→ low fidelity (100 kc) optimization, high fidelity (400 kc) validation



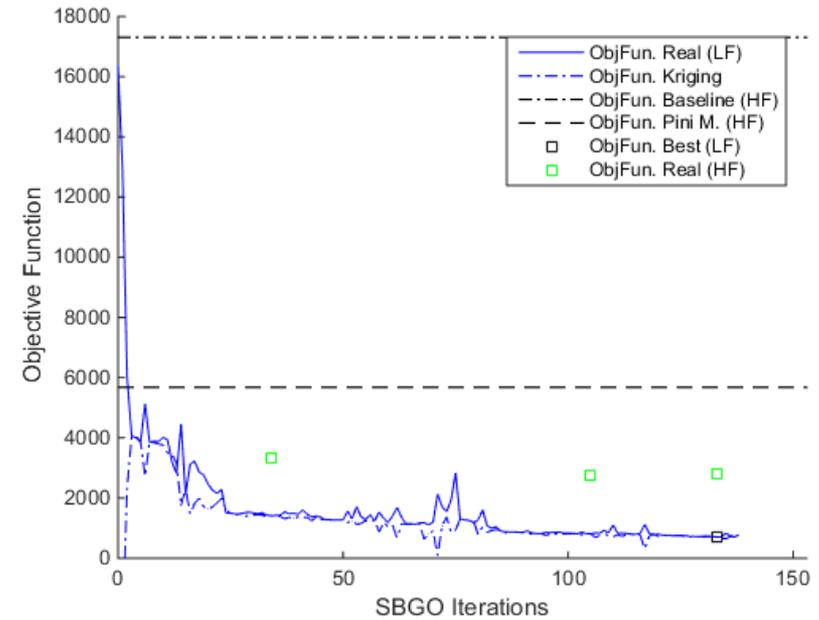
# Exercise of Design

## Convergence history

Local



**Global**



**Convergence** attained by both methods → nearly identical min OF (and blade!)

Global-Cost  $\approx$  20 h (16 proc. Cluster); Local-Cost  $\approx$  3  $\times$  Global-Cost

LF optimization proved to be reliable when verified in HF (very well matched trend)

# Optimization Results

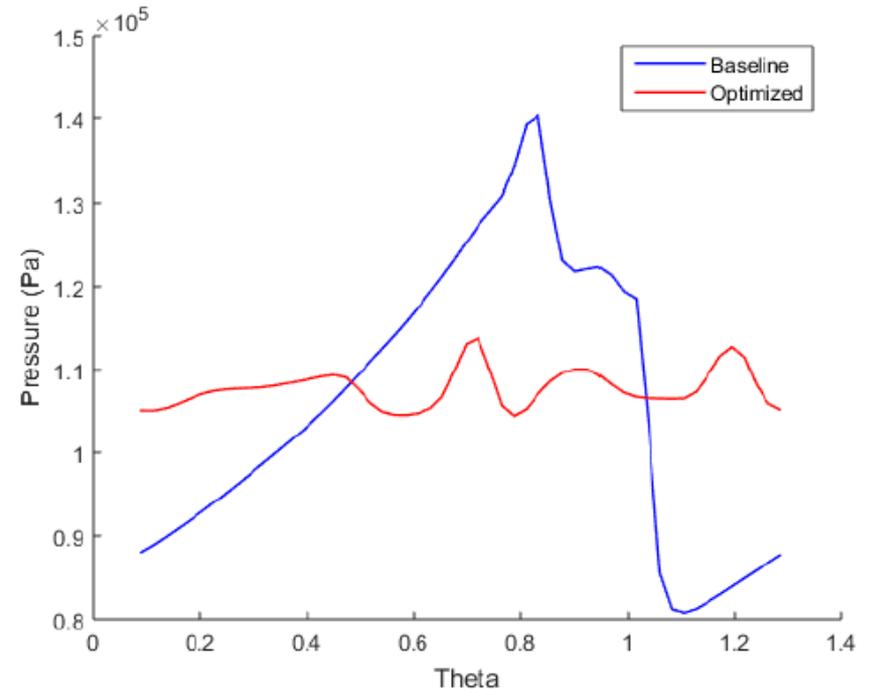
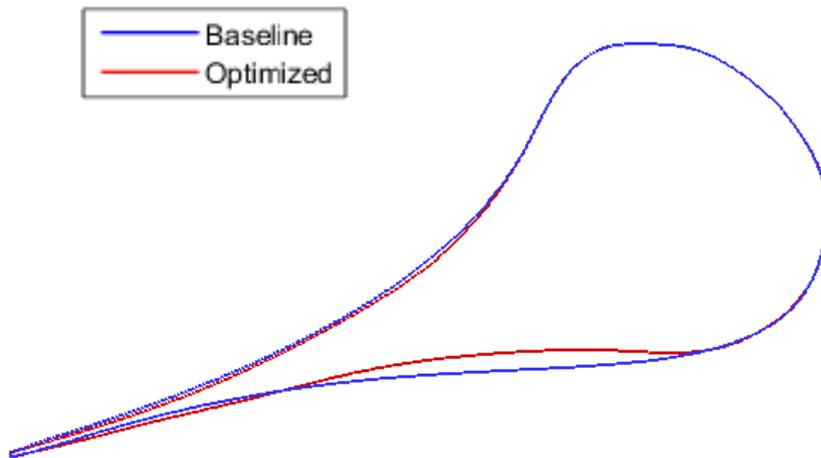
## Outcome

Optimized configuration

Enhanced divergence

→ Nearly uniform Pressure downstream

→ Dramatic shock reduction

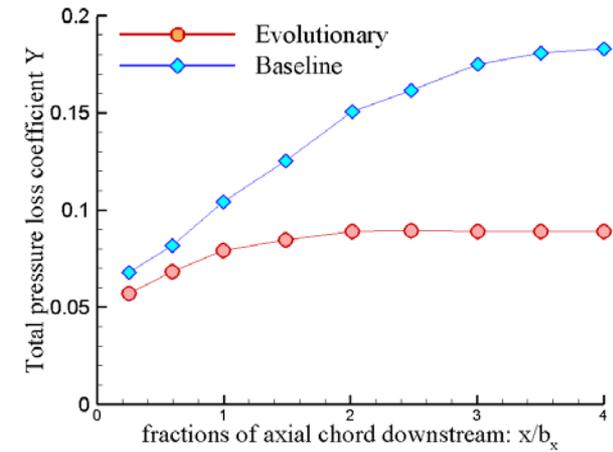
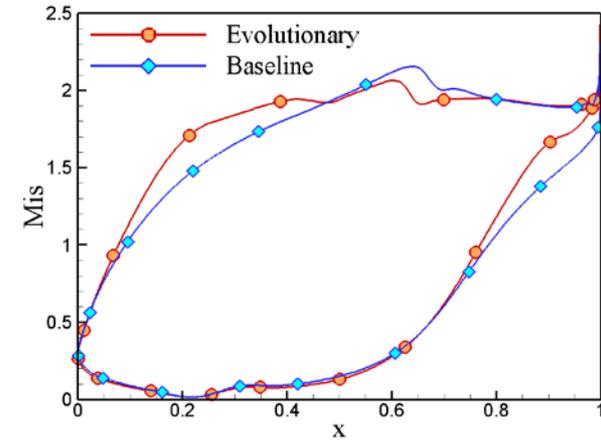
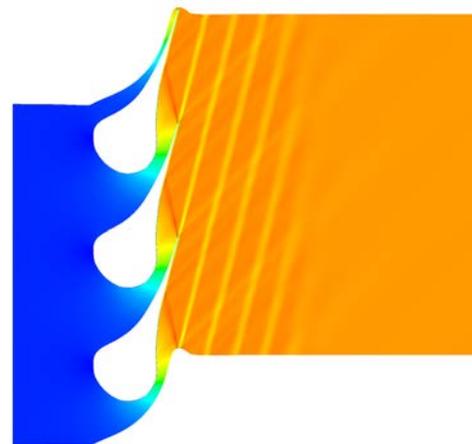
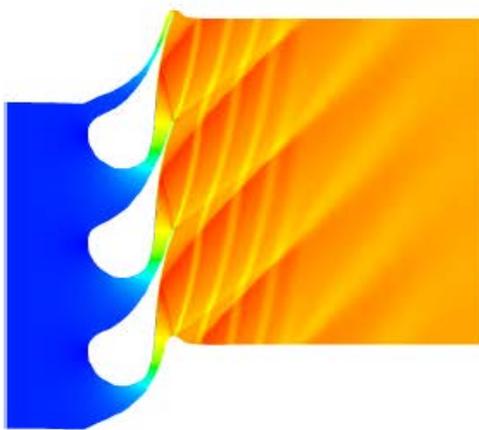
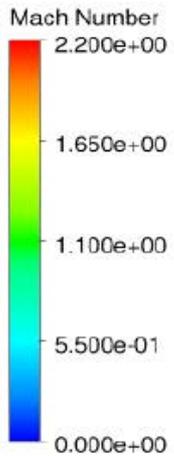
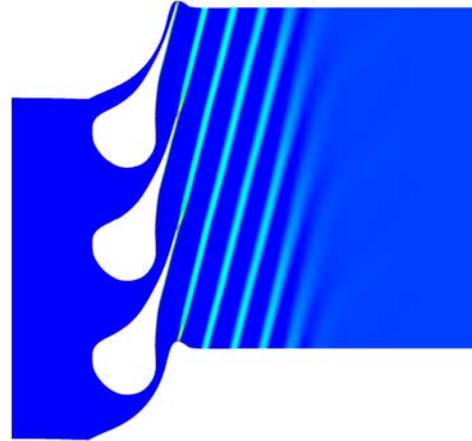
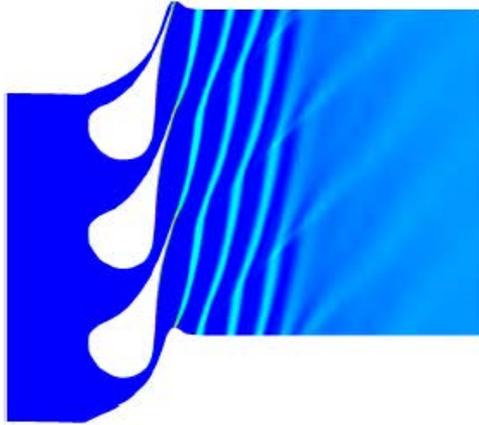
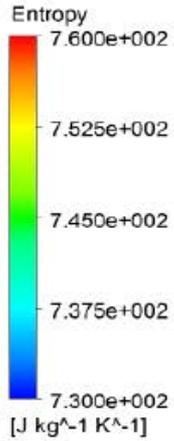


# Optimization Results

## Flow field and performance

Baseline

Optimized

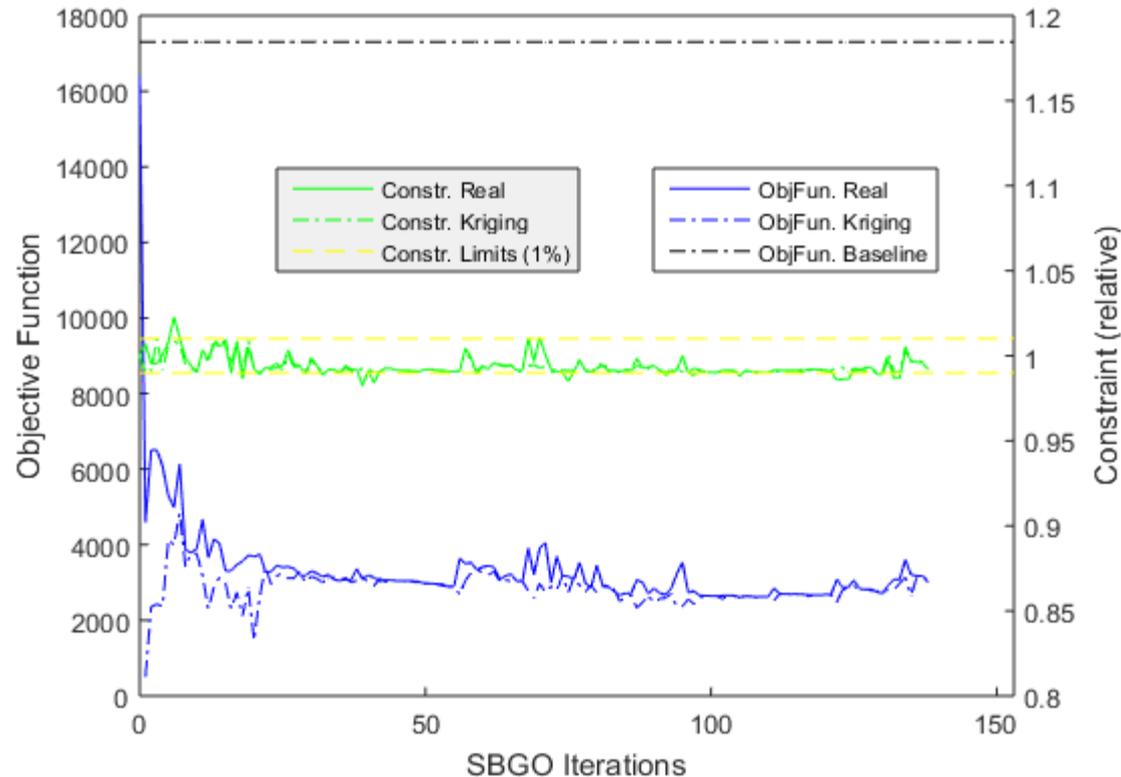


	<i>Baseline</i>	<i>Evolutionary</i>
<i>Y</i>	15%	8.9%

# Constrained Optimization

1% of flow rate

Convergence history



Surrogate model constructed also for the constrained quantity

Convergence attained but outcome slightly worse than non-constrained optimization

Non-constrained optimal blade satisfies flow rate constraint by fixed CPs up to throat

→ Geometrical constraint more effective than process constraint (choked flow)

# Robust Design

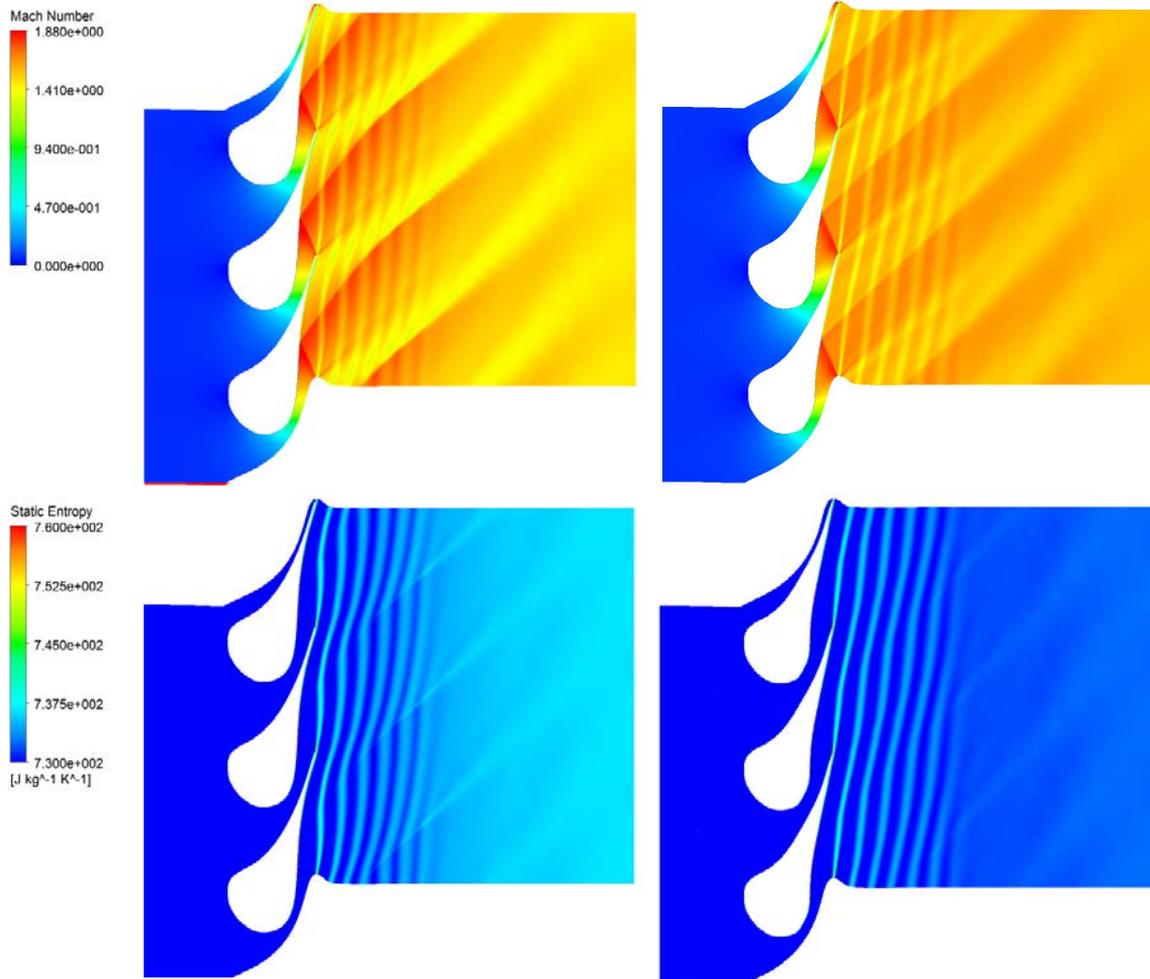
Multi-point Objective Function:

Standard deviation of P combining 2 or 3 operating conditions (possibly weighted)

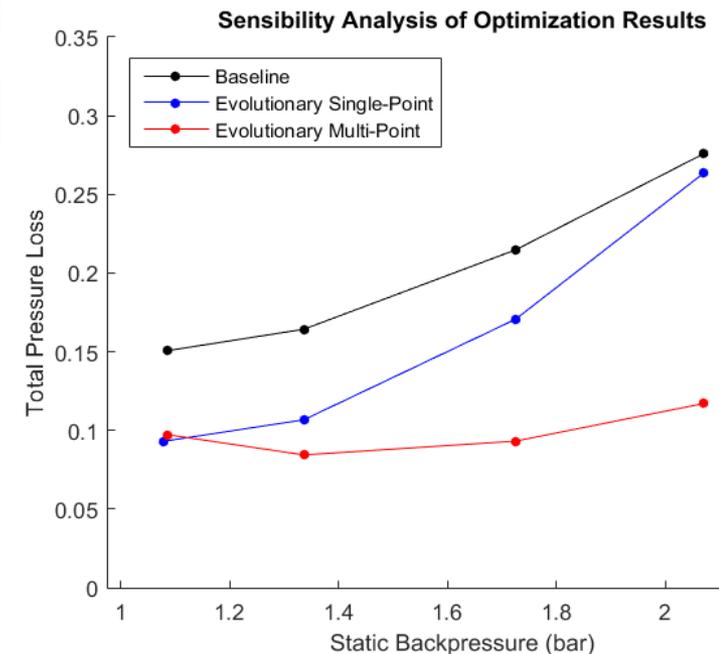
Baseline

Optimized

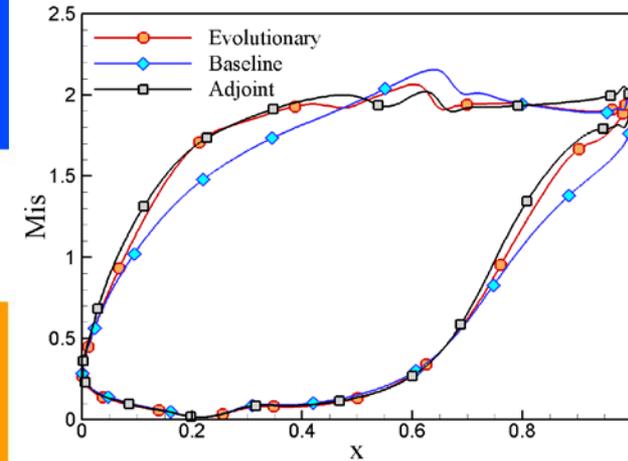
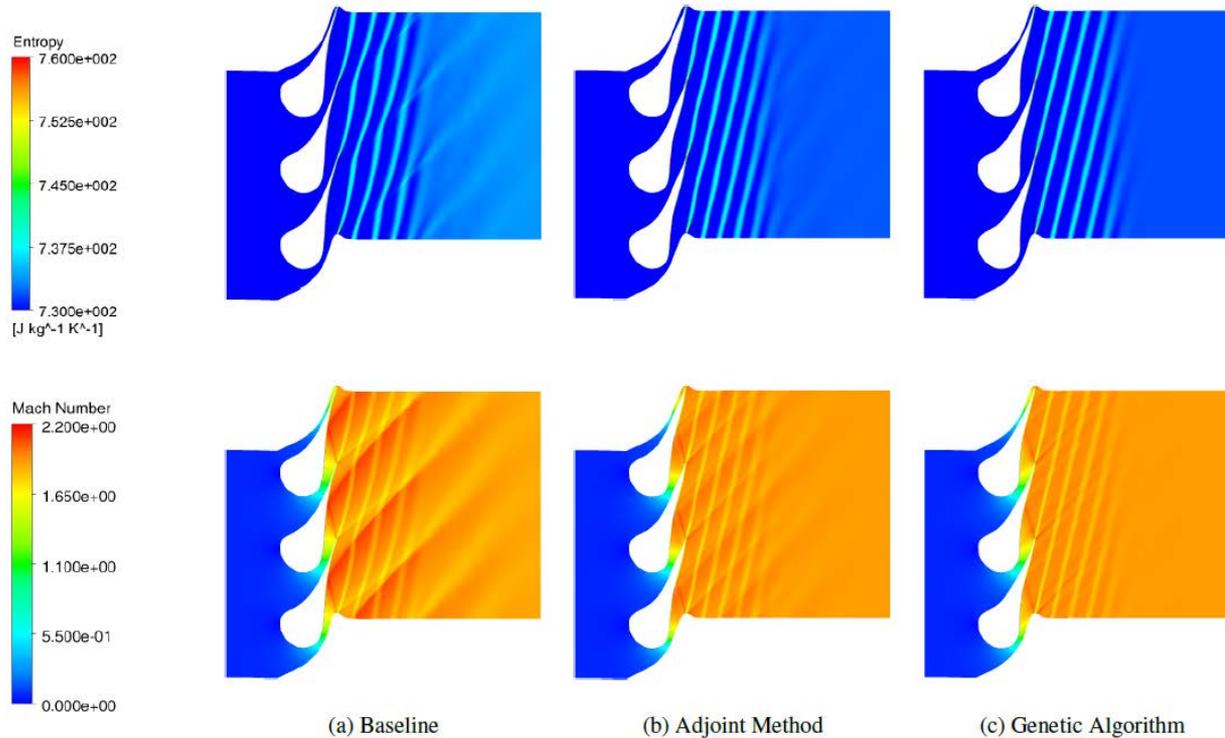
worst scenario ( $\beta = 0.5 \beta_{DES}$ )



$\beta$ -loss curves (off-design)



# Outcome of Evolutionary Optimization similar to Outcome of Adjoint-based Gradient Optimization



	<i>Baseline</i>	<i>Evolutionary</i>	<i>Adjoint</i>
<i>Y</i>	15%	8.9%	10.7%

# Conclusions

- High-fidelity methodology for ORC turbine design developed and applied
- Package: genetic algorithm, surrogate model, CFD, geometry parametrization
- Two surrogate-based strategies tested and proved to provide similar outcome
- Successful optimization (40% loss reduction), with 20 h of computational cost
- Constrained optimization developed, even though preventing full minimization
- Successful implementation for robust (i.e., multi-point) design

Thank you!  
Any questions?

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